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1.5 Linearization of the valve shows that $v = 4v_3 - 0.001u$.

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$D(q-1)A(q-1)[-T(t)(\tilde{t}+1)]$ (3.161) and the
parameter adaptation algorithm satisfying the passivity
condition will take the form: (\hat{t})

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$+1) = \hat{y}(t) + F(t) - y(t+1)$ (3.162) The equivalent feedback representation associated with the output error predictor using the above PAA is shown in Fig. 3.9.

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